عنوان مقاله:

A graph theoretic approach to controllablility of positive bilinear systems

محل انتشار:

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خلاصه مقاله:

In this paper, we show how graph theory can check necessary and sufficient conditions the basis for controllability of structural positive bilinear systems These conditions are one way simplify to check by hand for small systems and so we can use for large scale systems by means well-known combinatorial techniques

کلمات کلیدی: Positive bilinear systems, Controllability, graph theory

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