

**عنوان مقاله:**

dynamic modeling of a highly stable articulated rover

**محل انتشار:**

هفدهمین کنفرانس سالانه مهندسی مکانیک (سال: 1388)

تعداد صفحات اصل مقاله: 7

**نویسندگان:**

s.ali a moosavian - *associated professor*

ali rezvanifar - *graduate student k.n.toosi univ*

**خلاصه مقاله:**

In this paper the general dynamics model of a proposed articulated terrain rover (ATR) is developed. This rover has been designed for traversing on rough terrain and posses a highly stable structure on the terrain with an adaptable . articulated chassis on the terrain

**کلمات کلیدی:**

articulated terrain rover, kinematics, dynamics

**لینک ثابت مقاله در پایگاه سیویلیکا:**

<https://civilica.com/doc/90536>

